



ESP32 Workshop

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April 27, 2019
SVFIG



Maker Faire

May 18-19, 2019

- **We will get a 10'x20' booth.**
- **4 Workstations to teach people how to program ESP32 in Forth.**
- **Robot control through WiFi.**
- **Esp32forth demo.**
- **Short presentations on Forth programming.**



2019 Maker Faire

- **We need 4 assistants to manage the booth for Saturday morning and afternoon, and Sunday morning and afternoon.**
- **We need speakers to make short presentations on the hour in Saturday and Sunday.**

ESP32 WiFi

Microcontroller Workshop

- **Booth #69322**
 - **Friday 1-5 pm**
 - **Saturday 10 am - 6 pm**
 - **Sunday 10 am - 6 pm**
- **Presentation #70167**
 - **Sunday 1-3 pm**



2020 Maker Faire

- **We need a master maker to design, apply, and manage a booth for 2020 Maker Faire.**



Summary

- **Affordable microcontroller kits**
- **NodeMCU ESP32S kit**
- **Arduino IDE**
- **AIR robot**
- **Plan-B robot**
- **Serial Monitor interface**
- **Web Browser interface**
- **Bach benchmark**



Affordable Microcontroller Kits

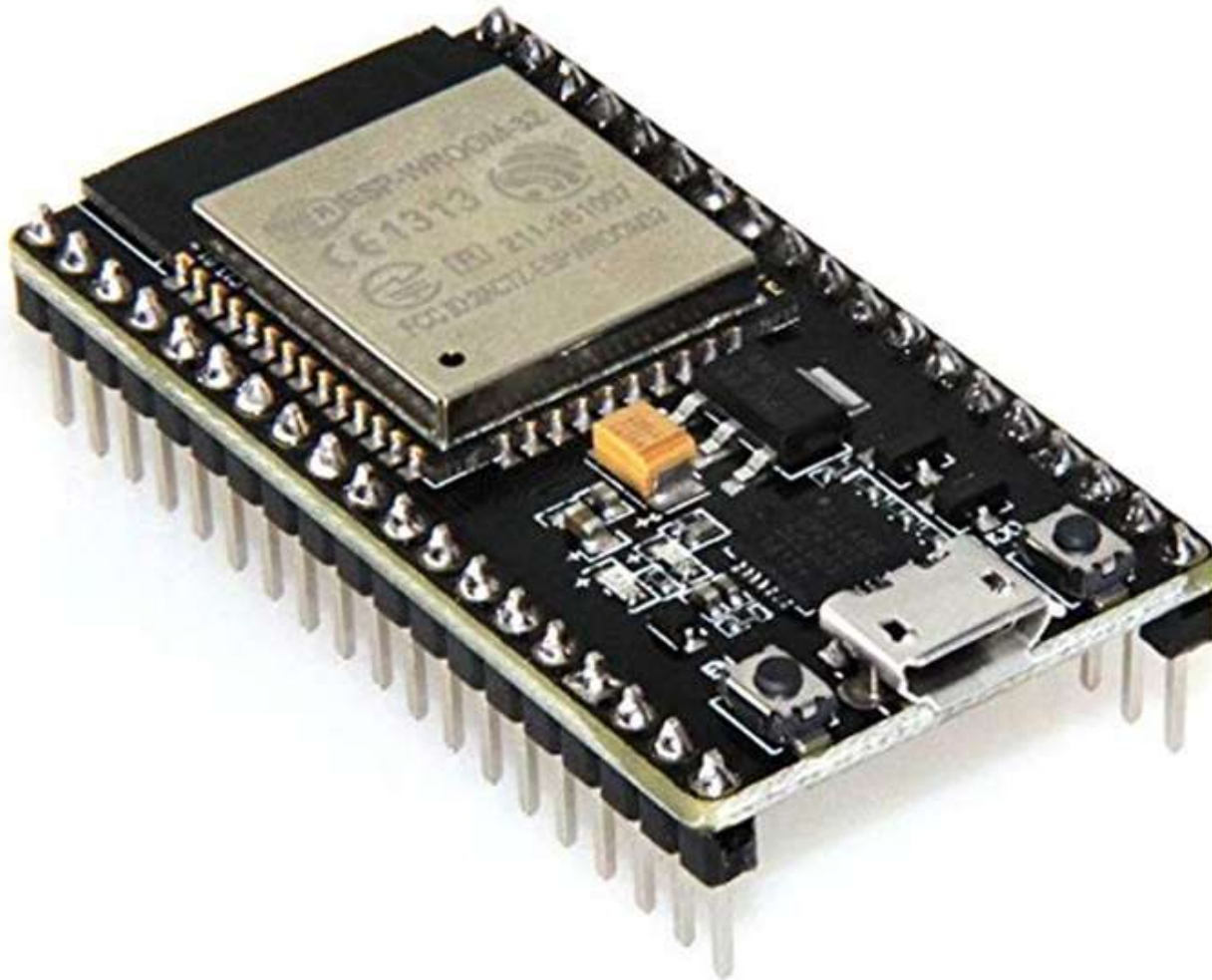
- **2005 ADuC7020**
- **2009 STM8 Discovery**
- **2011 TI LaunchPad MSP430**
- **2014 STM32 Discovery**
- **2015 Arduino Uno ATmega328P**
- **2017 NodeMCU ESP8266**
- **2019 NodeMCU ESP32**



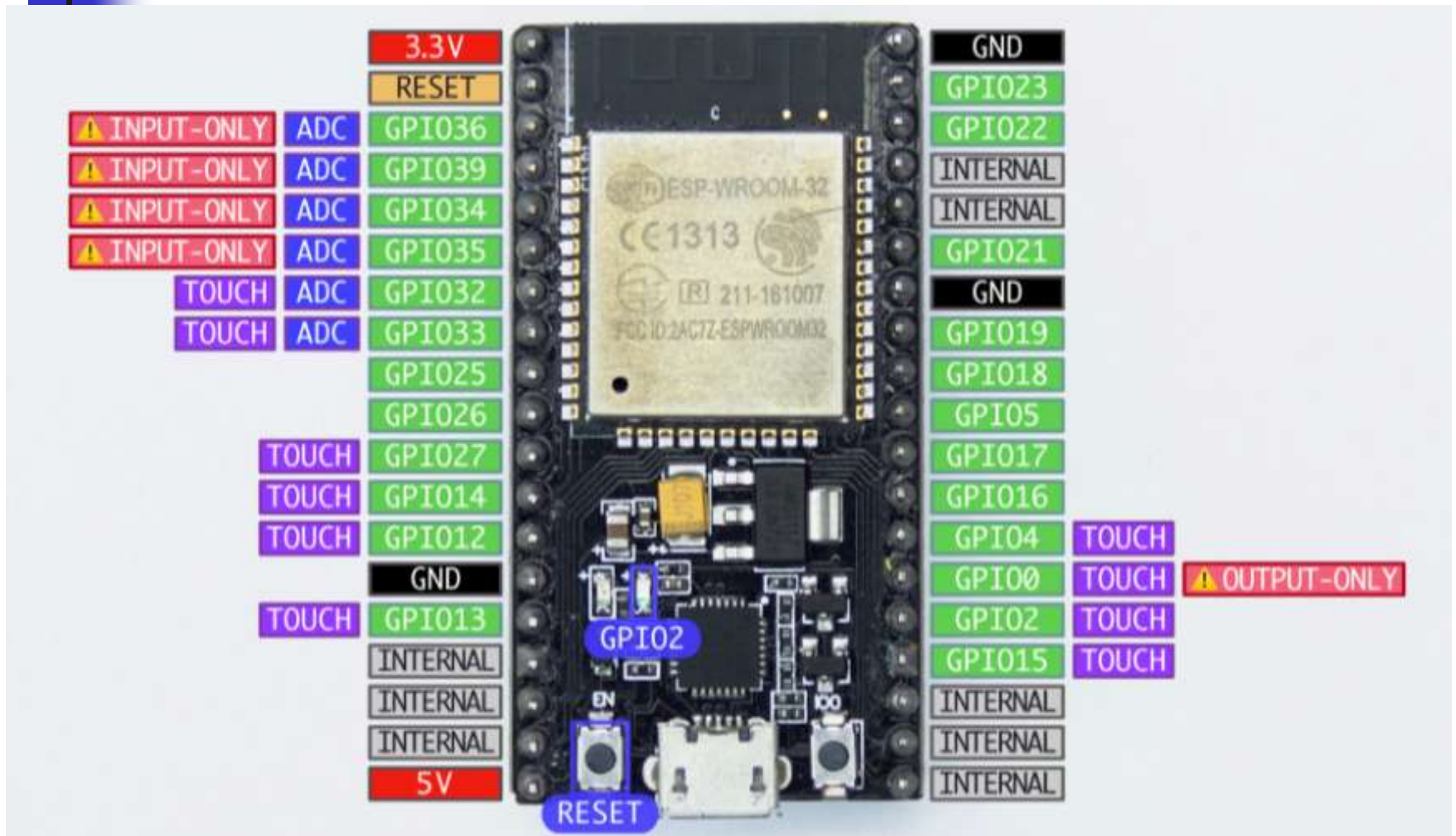
ESP32

- **Dual 32-bit Xtensa LX106, 240 MHz**
- **520 KB SRAM, 4 MB flash**
- **28 GPIO pins, 16 PWM channels**
- **8 ADC, 2 DAC, 3 UART, 2 SPI, 3 I2C**
- **WiFi: IEEE 802.11 b/g/n/e/I**
- **Bluetooth**

NodeMCU ESP32S



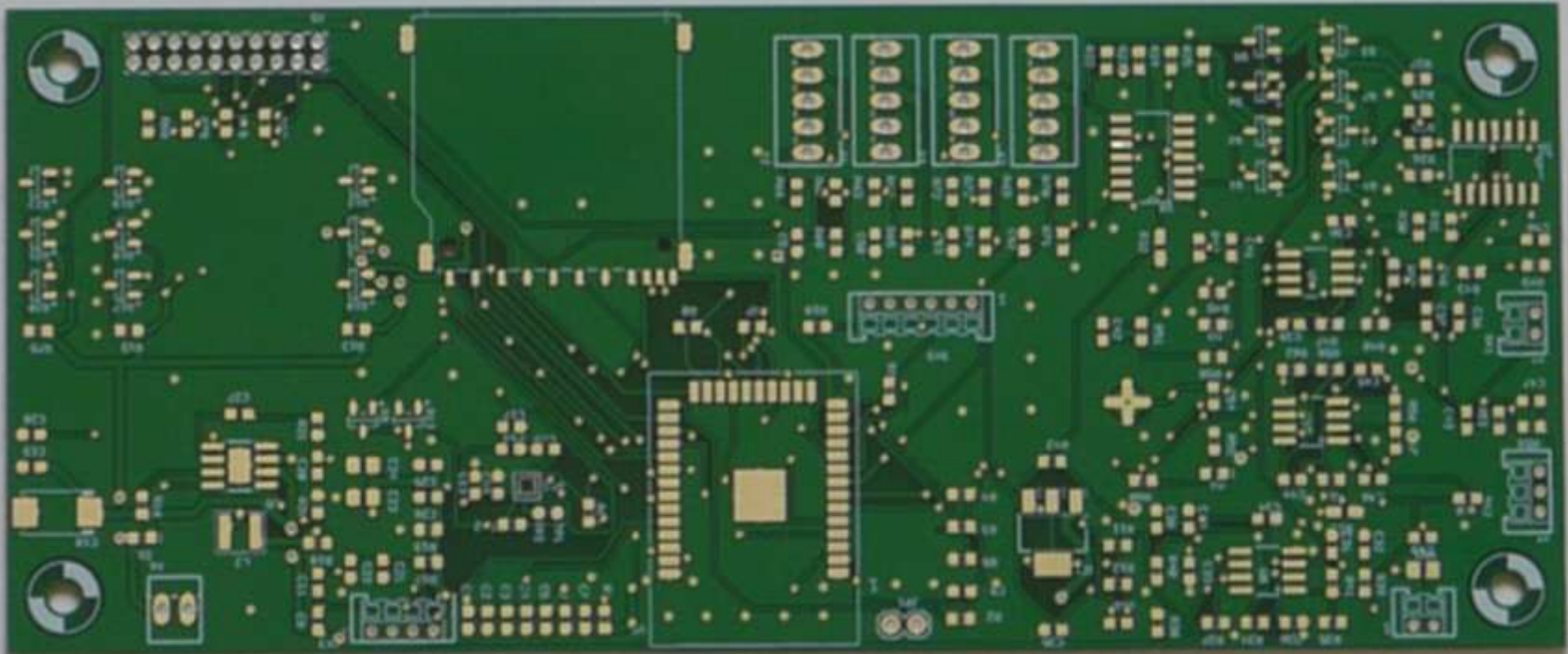
NodeMCU ESP32S





AIR-AI Robot

- **Ron Golding is building his AIR Robot for Maker Faire.**
- **So far, I have only seen a bare PC board.**





Plan-B Robot

- **I received a number of robot car kits from Taiwan FIG.**
- **I assembled two robot car kits for Maker Faire.**
- **Both use NodeMCU ESP32S kits as controllers.**
- **I tested motors, obstacle sensors, and speaker.**



ESP32forth

- **ESP32forth emulates eP32, a 32-bit Forth microcontroller.**
- **Virtual Forth Machine executes byte code, and is written in C as a sketch.**
- **ESP32forth Finite State Machine:**

```
{primitives [char cData [P++]] ();}
```



Serial Monitor Interface

- **NodeMCU ESP32S is connected to Arduino IDE through a microUSB cable.**
- **User test and program ESP32 through the Serial Monitor at 11520 baud.**
- **Turnkey application is placed in load.txt file stored in flash.**

COM3

Send

WiFi connected
SSID:
IP Address: 0.0.0.0
signal strength (RSSI):0 dBm
Starting connection to server...
Local Port: 10009
Booting esp32Forth_52 ...

esp32forth V5.2, 2019

0 0 0 0 ok>words

IMMEDIATE COMPILE-ONLY (\ .(CONSTANT VARIABLE CREATE CODE ." \$" ABORT" WHILE ELSE AFT REPEAT AHEAD
IF AGAIN UNTIL NEXT BEGIN FOR THEN FUGUE3 L12 M72 M71 M70 M69 M68 M67 L11 M66
M65 M64 M63 M62 M61 L10 M60 M59 M58 M57 M56 M55 L9 M54 M53 M52 M51
M50 M49 L8 M48 M47 M46 M45 M44 M43 L7 M42 M41 M40 M39 M38 L6 M37
M36 M35 M34 M33 M32 L5 M31 M30 M29 M28 M27 L4 M26 M25 M24 M23 M22
M21 L3 M20 M19 M18 M17 M16 M15 L2 M14 M13 M12 M11 M10 L1 M9 M8
M7 M6 M5 M4 M3 M2 M1 TR %% % // / FUGUE2 L16 M84 M83 M82
M81 M80 M79 L15 M78 M77 M76 M75 M74 L14 M73 M72 M71 M70 M69 L13 M68
M67 M66 M65 M64 L12 M63 M62 M61 M60 M59 L11 M58 M57 M56 M55 M54 L10
M53 M52 M51 M50 M49 L9 M48 M47 M46 M45 M44 L8 M43 M42 M41 M40 M39
L7 M38 M37 M36 M35 M34 L6 M33 M32 M31 M30 M29 L5 M28 M27 M26 M25
M24 L4 M23 M22 M21 M20 M19 L3 M18 M17 M16 M15 M14 L2 M13 M12 M11

Autoscroll Show timestamp

Newline

115200 baud

Clear output



Web Browser Interface

- **I was using very simple HTTP protocol to send Forth commands to the robot.**
- **Brad Nelson changed it to Web server and implemented a true browser to send commands and to download text files.**



Web Browser Interface

- **ESP32forth is extended so that user can operate ESP32 through HTTP web browser.**
- **All interactive interpreter and compiler functions**
- **Direct robot control**
- **Source code file download**

esp32forth5.6

Upload File:

```

0 0 0 0 ok>
TONES UPDOWN BIRD WAIL vWAIL WARBLE LASER RIDE BLOW 3/8 3/4 1/8 1/2 1/4 ppqn@ NOTE IMMEDIATE
COMPILE-ONLY ( \ .( CONSTANT VARIABLE CREATE CODE ." $" ABORT" WHILE ELSE AFT REPEAT AHEAD IF
AGAIN UNTIL NEXT BEGIN FOR THEN 3/32 3/16 3/8 3/4 3/2 1/128 1/64 1/32 1/16 1/8 1/1
1/2 1/4 ppqn@ C2 D2b C2# D2 E2b D2# E2 F2 G2b F2# G2 A2b G2# A2
B2b A2# B2 C3 D3b C3# D3 E3b D3# E3 F3 G3b F3# G3 A3b G3# A3
B3b A3# B3 C4 D4b C4# D4 E4b D4# E4 F4 G4b F4# G4 A4b G4# A4
A4# B4b B4 C5 D5b C5# D5 E5b D5# E5 F5 G5b F5# G5 A5b G5# A5
B5b A5# B5 C6 HUSH INIT PLAY notes DELAY KKK PPPP TYPEE EMITT PPP P1IN P0IN P1ENC
P1ENS P1EN P0ENC P0ENS P0EN P1C P1S P1 P0C P0S P0 PP LINE HI FORGET WORDS .ID
>NAME DUMP dm+ ; : ] OVERT $COMPILE COMPILE [COMPILE] '$,n ?UNIQUE $," ALLOT LITERAL ,
LOAD EVAL .OK [ $INTERPRET ERROR abort" QUERY EXPECT NAME? find SAME? NAME> WORD TOKEN PARSE PACK$
(parse) ? . U. U.R .R ."| $"| do$ CR TYPE SPACES CHARS SPACE NUMBER? DIGIT? >upper
wupper DECIMAL HEX str #> SIGN #S # HOLD <# EXTRACT DIGIT FILL MOVE CMOVE @EXECUTE TIB
PAD HERE ALIGNED >CHAR WITHIN FREQ DUTY TONE PIN ADC PEEK POKE sendPacket 2/ 2* 2- 2+
1- 1+ CELL/ CELLS CELL- CELL+ CELL BL MIN MAX COUNT 2@ 2! +! PICK */ */MOD
M* * UM* / MOD /MOD M/MOD UM/MOD < U< = ABS - DNEGATE NEGATE NOT +
2DUP 2DROP ROT ?DUP UM+ XOR OR AND 0< OVER SWAP DUP DROP >R R@ R> C@
C! @ ! BRANCH QBRANCH DONEXT EXECUTE EXIT DOLIST DOLIT EMIT ACCEPT BREAK channel ppqn Z tmp
'ABORT 'EVAL LAST CP CONTEXT BASE 'TIB #TIB >IN SPAN HLD
0 0 0 0 ok>

```



Bach Benchmark

- **In 1984, a friend in Taiwan FIG gave me an PC IO Card with 4 8253s and 4 8255s, for machine automation.**
- **I built a 12 channel electronic organ, and played many organ pieces by Bach.**



Robot Control Buttons

- **INIT** **Initialize speaker**
- **RIDE** **Speaker demo**
- **FORE** **Drive robot forward**
- **BACK** **Drive robot backward**
- **LEFT** **Drive robot left**
- **RIGHT** **Drive robot right**
- **STOP** **Stop robot**
- **LED** **Turn on blue LED**
- **ADC** **Test 4 analog inputs**



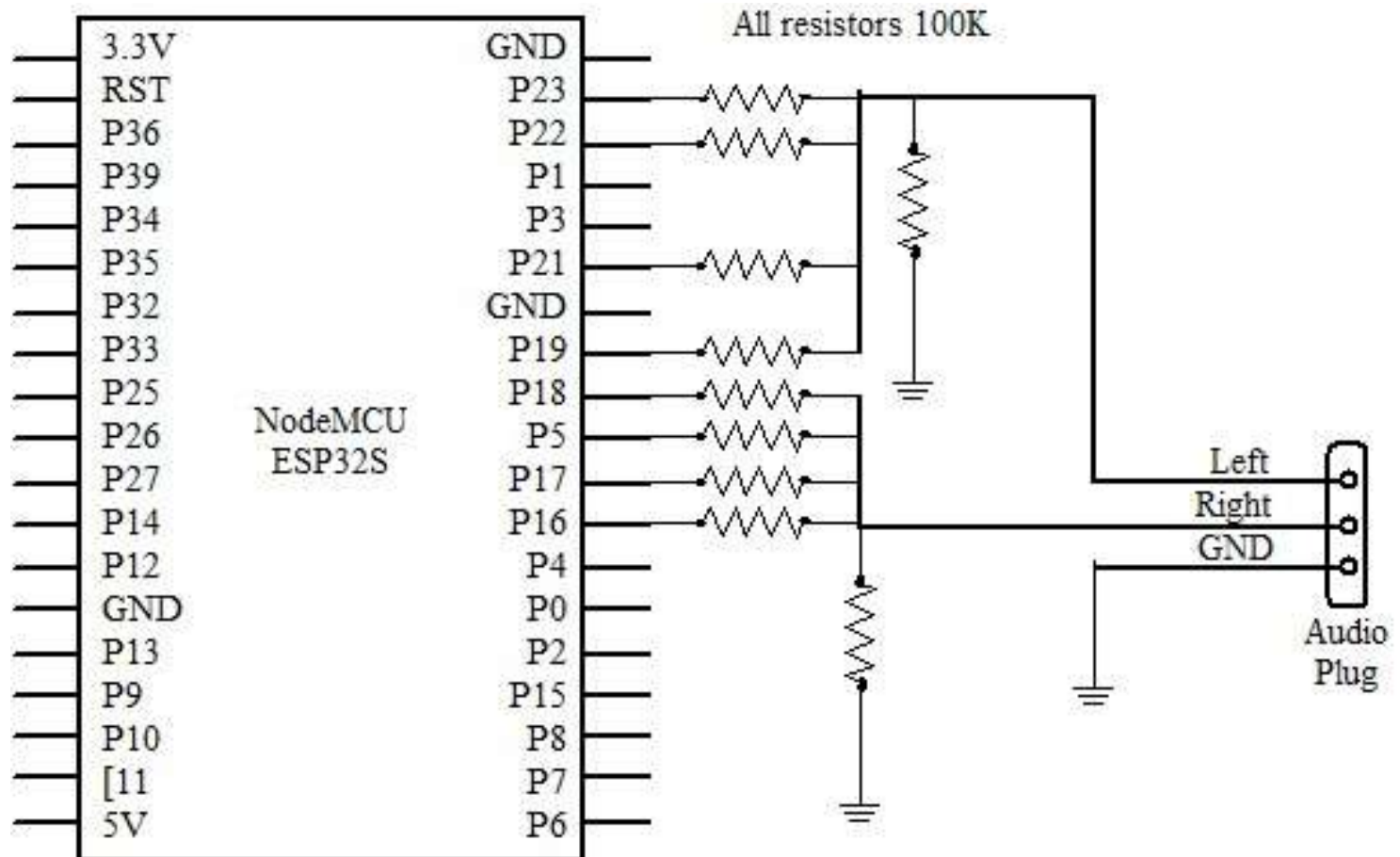
Bach Benchmark

- **I tried to play Bach organ music on most of the microcontrollers I worked with.**
- **Only Arduino Uno could play three-voice organ pieces.**
- **ESP32 can play 8 voices, and passes my Bach Benchmark.**

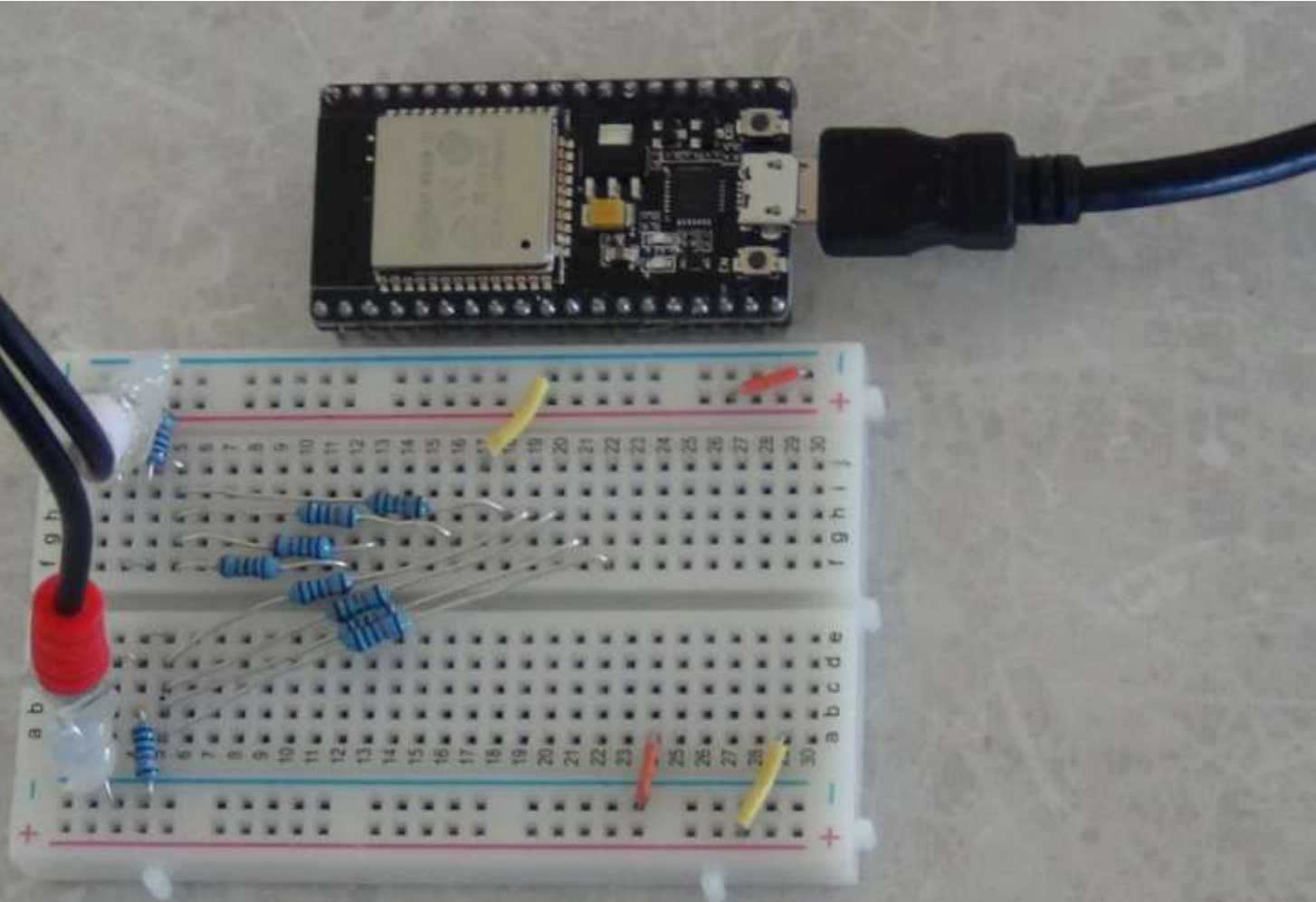
Electronic Organ



Electronic Organ



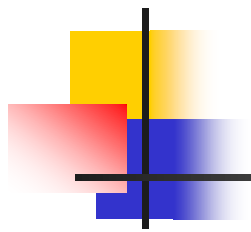
Electronic Organ





Organ Demo

- **8 Channel electronic organ**
- **8 Digital outputs are summed to a left voice and a right voice through an array of 100K Ω resistors.**
- **Left and right voices are amplified by a speaker.**
- **A musette dance and a fugue.**



Questions?

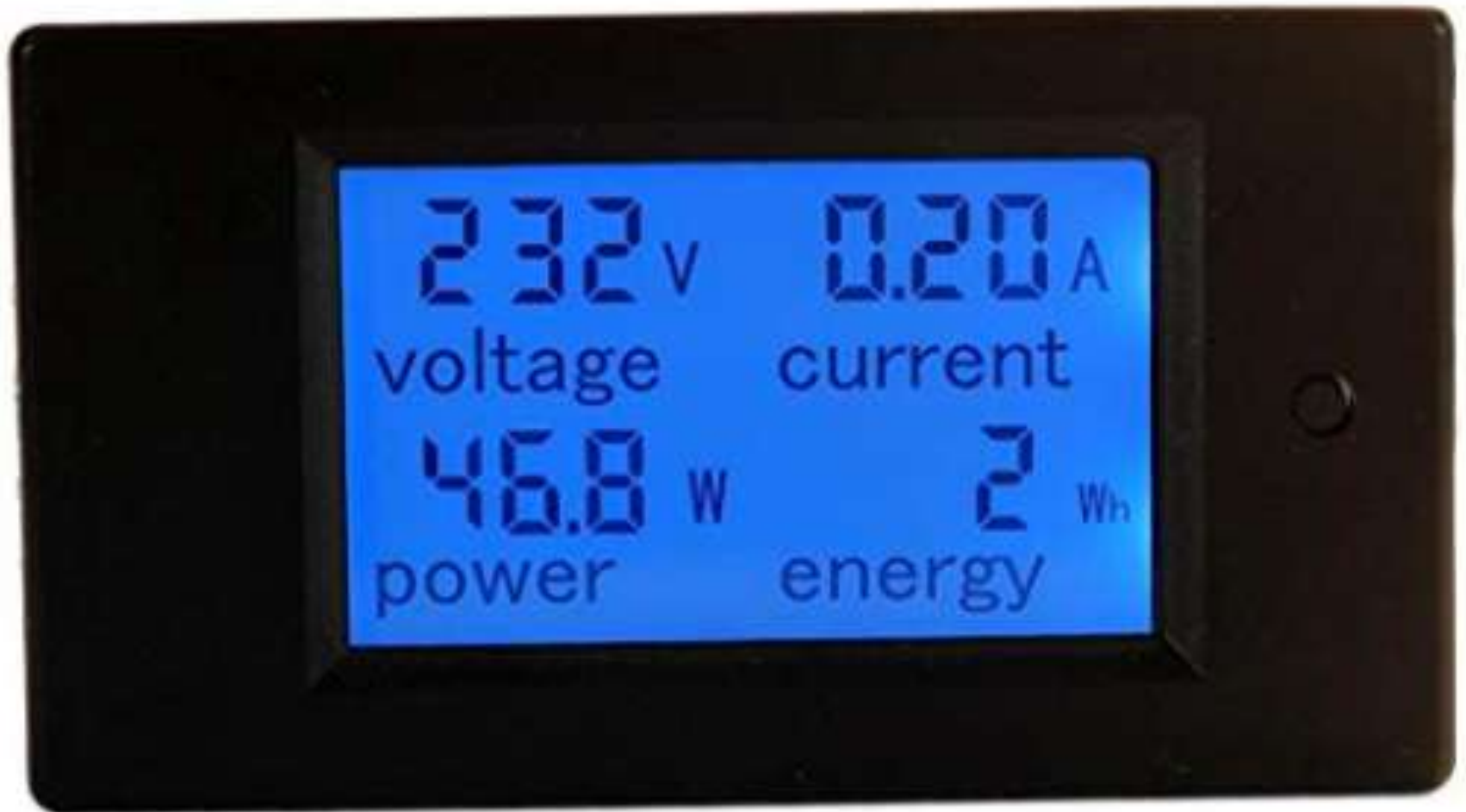


AC Power Meter

- **HiLetgo Digital Multimeter AC 80-260V 100A PZEM-061**
- **LCD Display**
- **Digital Current Voltage Power Energy Multimeter**



AC Power Meter





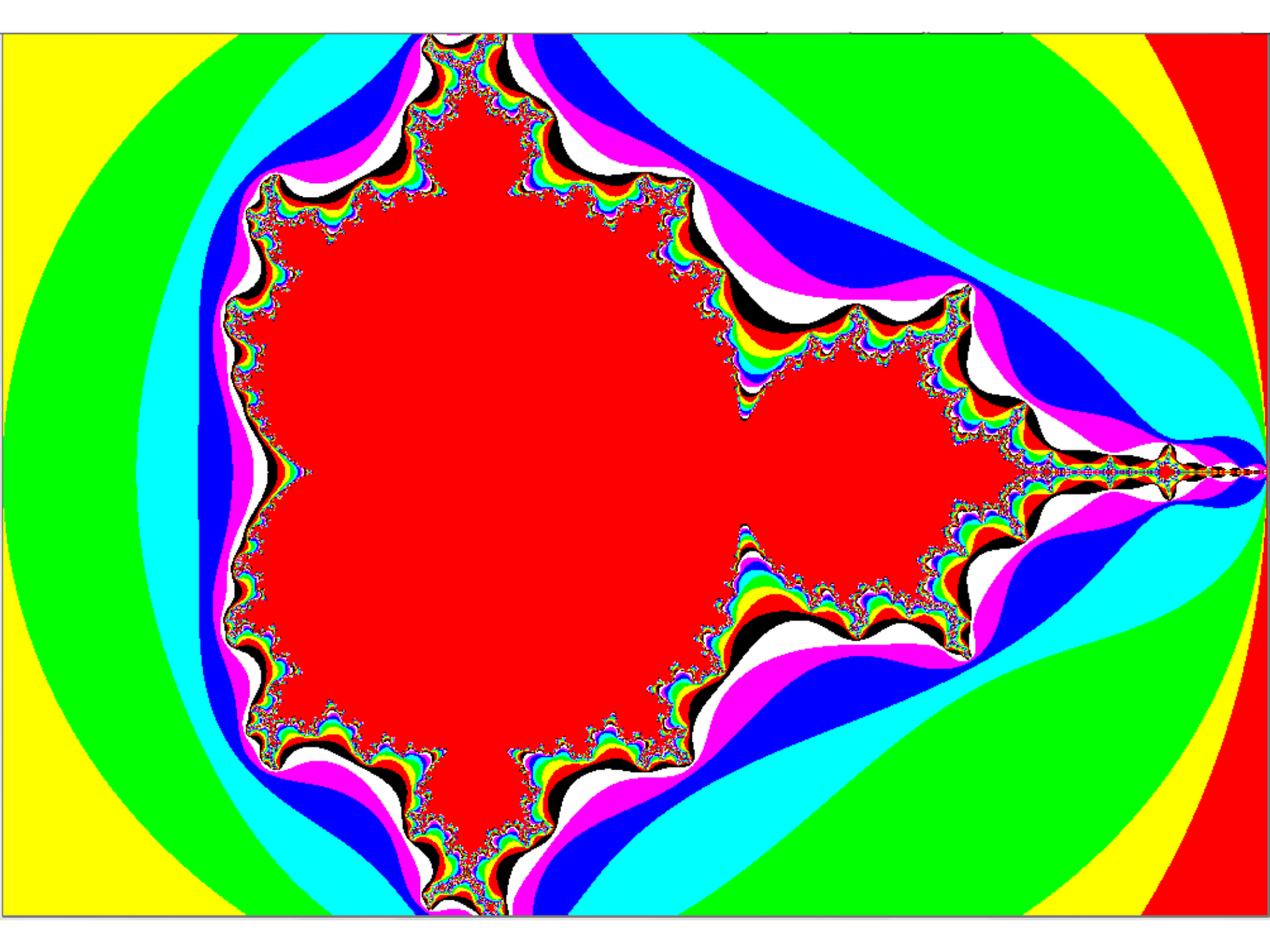
Python Mandelbrot

- **I had the Forth program to draw colored digital world maps.**
- **I used Python CV2 to piece together a short video showing the rotating earth.**

mandelbrot_5.py - C:\demo\mandelbrot_5.py (3.7.2)

File Edit Format Run Options Window Help

```
import cv2
import numpy as np
title='Mandelbrot'
width=1000
height=700
iteration=25
a=255
palette=np.array([[0,0,0],[0,0,a],[0,a,a],[0,a,0],
                 [a,a,0],[a,0,0],[a,0,a],[a,a,a]],dtype=np.uint8)
picture=np.zeros((700,1000,3),dtype=np.uint8)
def mandelbrot(x,y):
    z = [0,0]
    for n in range(iteration):
        re=z[0]**2
        im=z[1]**2
        z[1] =y+2*z[0]*z[1]
        z[0] = re - im + x
        if re+im > 4:
            return n
    return iteration
def mm(x,y,d):
    for n in range(height):
        for m in range(width):
            i=mandelbrot((m-width/2)*d+x,(n-height/2)*d+y)
            picture[n,m]=palette[i&7]
    title='Mandelbrot Set: x=%2.8f y=%2.8f d=%2.8f' % (x,y,d)
    cv2.imshow(title,picture)
mm(-0.5,0,0.003)
```



Digital World

- **I had the Forth program to draw colored digital world maps.**
- **I used Python CV2 to piece together a short video showing the rotating earth.**



Digital World

idcw_2.py - C:\F#\globe\idcw_2.py (3.7.2)

File Edit Format Run Options Window Help

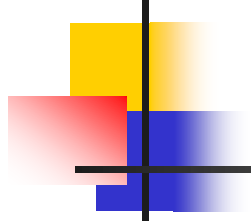
```
import numpy as np
import cv2,os

files=os.listdir() ## 360 dat files
height=512
width=768
out = cv2.VideoWriter('world.avi',cv2.VideoWriter_fourcc('M','J','P','G'), 30, (
for i in range(360):
    print(i)
    f = open(files[i+1], 'rb')
    img = bytearray(f.read())
    f.close()
    image=np.reshape(img,(height,width,3))
    out.write(image)
out.release()
```



MIDI and Karaoke

- **Dr. Lue Liu gave me 500 songs from his HymnMaster player.**
- **I converted these song files into MIDI files.**
- **I can now add lyrics and build Karaoke files.**



Thank you.